BUS: THE DATA HIGHWAY

The word hus came from latinomnibus meaning (in the public transport sense) for every body but here in computer hardware it means for every device.

Bus is typically a row of standardized parallel conducting paths (wires) or strips on a PCB, which links modular components, processors, peripherals, registers and provides data transport.

In strict sense, the definition applies only to the interconnection of microprocessor and memory. A bus includes power and signal conductors to energize all functional parts of the computer and allow them to communicate with each other. Buses are operated under a strict set of data communication rules

Why bus ?

Bus offers many advantages over haphazard connection, this include, protection of components from overload conditions, modularity, high fan-out and standardization.

Bue Width

The number of hits that can be transmitted simultaneously along the bus fin parallel fashion) is called the bus width or bus size. It depends on the size of the

Considering function, buses are divided into three main categories.

a) Control bus : It passes timing and initiating signals from one subsystem to another. It conveys timing signals. memory commands. I/O requests. interrupt request. It acknowledges idle signale

b) Data bus : Data bus carry specified number of data bits usually 8, 16 or 32. It is used to carry data from source register to destination register (i.e. betn microprocessor and memory). input and output lines on the memory unit are connected to it. Sometimes it is also called Bus Bar.

c) Address bus : This is an unidirectionat his which selects a memory location to which the microprocessor wish. es to use transfer operation. It is also used to select I/O controller.

According to construction, buses are of two kinds-Ribbon cable and Backplane, Ribbon cable is a kind of portable and flexible parallel wires, e.g. a 25 wire parallel cable. Backplane is an integral part of the frame of the computer, much like a plugboard into which other fundamental com-/O device

ponents are inserted On the basis of the direction of the data transfer. huces 910 Unidirectional and Bidirectional in an unidirectional bus, transfer proceedes only in one direction, e.g. address hus Whereas in hidirectional bus, transfer can proceed in both direction but not at the same time. le.g. data or control bus).

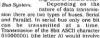


Fig : Simplified Block diagram of a typical Bus System. unit that the bus is connecting. A bus

connecting two m.bit registers must be at least m-bit wide. In reality the bus width is frequently

much larger than just the size of the registers to which it is connected. This is because in addition to transmitting binary data, the bus will also simultaneously transfer control and timing information or signals.

Since with the increase in length the technical problem such as impedance. signal propagation delay, reflecton arises hence Bus length is usualy half a meter or so. Now a days modular components are packed closer together for making shorter bus length.

Bit rate

The bit rate of a bus is usually measured by the number of bits per second (bps) that can be transmitted along the bus. Typical bit rate for serial bus are of the range of 100 to 50000 bos

A scrial bus is less speedy, as it transmits one bit at a time. Considering time factor parallel buses are used in computer system.

natral

One bit 0 0 0 0 0 0 1 0 17 10 10 10 10 10 11 Serial bus destination Serial buses are usually reserved for

eight separate 1 bit transmission.

external communication (communication to device that are located away from the main processor e.g. printer). A parallel bus transmits information simultaneously along the number of parallel paths. hence it is faster than serial bus. For a 8 bit parallel bus between source and distination the value 01000001 would be transmitted along the bus as-

8 bit OIIOOOOO source parallel V V V V V V

101110101010101011 destination

Conclusion

All the current bus structure have been designed with two goals in viewa. Standardization of the mechanical

the computer system, with the con-

comitant reduction in manufacturing

 Flexibility in system configuration. A bus standard specifies the upper and lower limits of the electrical signals carried by each bus group.

Bus terminologies

cost and

Multibus : This is the trade mark of IEEE 796 bus developed by INTEL. External bus : This provides a standard set of lines and a standard pin configuration to exchange data with external devices hooked to it i.e.

IEEE-488 bus. Mass bus : It supports specifically transfer between memory and mass

storage system Bus master : In shared or common bus structure a number of devices can be connected to the bus. During the transfer one of the device must take control of the transfer operation. This

device is called bus master and the other devices are called slave units. Memory bus : It handles all transfor between memory and the internal component of the computer much like a common bus.

References

1 Microcomputer system - Ivan Flowres and Christopoher

2. Microcomputer Interfacing

- Bruce A Artwick

3. The principle of computer organiza-

- G. Michael Scancider 4. Mini and Microcomputer system

- M. G. Hartley 5. Introduction to computer Engineering

- Taylor L. Booth 6. Introduction to computer system

- Glenn H. Macewen 7. A 60 Minute guide to Microcomputer - Lew Hollerbach



Call 815302 Omnifech

79 Satmasjid Road 1/F, Dharmondi, Dhaka